



Factorization Machines

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FM Overview

- Simon Funk, Funk MF
- Imputing missing values



Model

There are 2 matrices that have a dot product yielding a matrix R where the difference between R and our data is at a minimum

$$\begin{bmatrix} 1.2 \\ 1.3 \\ 1.5 \\ 2.2 \\ 1.6 \\ 1.0 \\ 1.4 \\ 1.4 \\ 1.6 \end{bmatrix} * [2 \quad 1.7 \quad 2.2 \quad 1.3 \quad 1.7] \approx \begin{bmatrix} 2.3 & 2.0 & 2.6 & 1.5 & 2.0 \\ 2.6 & 2.3 & 3.0 & 1.7 & 2.2 \\ 2.9 & 2.6 & 3.3 & 1.9 & 2.5 \\ 4.4 & 3.8 & 5.0 & 2.9 & 3.7 \\ 3.1 & 2.7 & 3.5 & 2.0 & 2.6 \\ 2.0 & 1.7 & 2.2 & 1.3 & 1.7 \\ 2.7 & 2.4 & 3.1 & 1.8 & 2.3 \\ 2.7 & 2.4 & 3.1 & 1.8 & 2.3 \\ 3.2 & 2.8 & 3.7 & 2.1 & 2.7 \end{bmatrix}$$



Why would a derived matrix be useful?



Model

If a matrix exists that looks similar to our data, surely we would want to find it and borrow from it?

$$R = \begin{bmatrix} 2.3 & 2.0 & 2.6 & 1.5 & 2.0 \\ 2.6 & 2.3 & 3.0 & 1.7 & 2.2 \\ 2.9 & 2.6 & 3.3 & 1.9 & 2.5 \\ 4.4 & 3.8 & 5.0 & 2.9 & 3.7 \\ 3.1 & 2.7 & 3.5 & 2.0 & 2.6 \\ 2.0 & 1.7 & 2.2 & 1.3 & 1.7 \\ 2.7 & 2.4 & 3.1 & 1.8 & 2.3 \\ 2.7 & 2.4 & 3.1 & 1.8 & 2.3 \\ 3.2 & 2.8 & 3.7 & 2.1 & 2.7 \end{bmatrix}$$

Our data = $\begin{bmatrix} 2 & ? & ? & ? & 2 \\ ? & ? & 3 & 2 & ? \\ 3 & ? & ? & ? & ? \\ 4 & 4 & 5 & 3 & 4 \\ ? & ? & ? & 2 & ? \\ 2 & 2 & 2 & 1 & 1 \\ 3 & ? & 3 & ? & ? \\ ? & ? & 3 & ? & 2 \\ 3 & 3 & ? & 2 & ? \end{bmatrix}$



Rating Imputation

Before imputing

		Service				
Users	1	2	?	?	?	?
	2	?	?	3	2	?
	3	?	?	?	?	?
	4	4	5	3	4	
	5	?	?	2	?	
	6	2	2	2	1	1
	7	3	?	3	?	?
	8	?	?	3	?	2

After imputing

		Service				
Users	1	2	2	3	2	2
	2	3	2	3	2	2
	3	3	3	2	3	
	4	4	5	3	4	
	5	3	3	4	2	3
	6	2	2	2	1	2
	7	3	2	3	2	2
	8	3	2	3	2	2



How do we find these factors?



How do we find these factors?

$\begin{bmatrix} ? \\ ? \\ ? \\ ? \\ ? \\ ? \\ ? \\ ? \end{bmatrix} * [? \quad ? \quad ? \quad ? \quad ?] :$

Gradient Descent

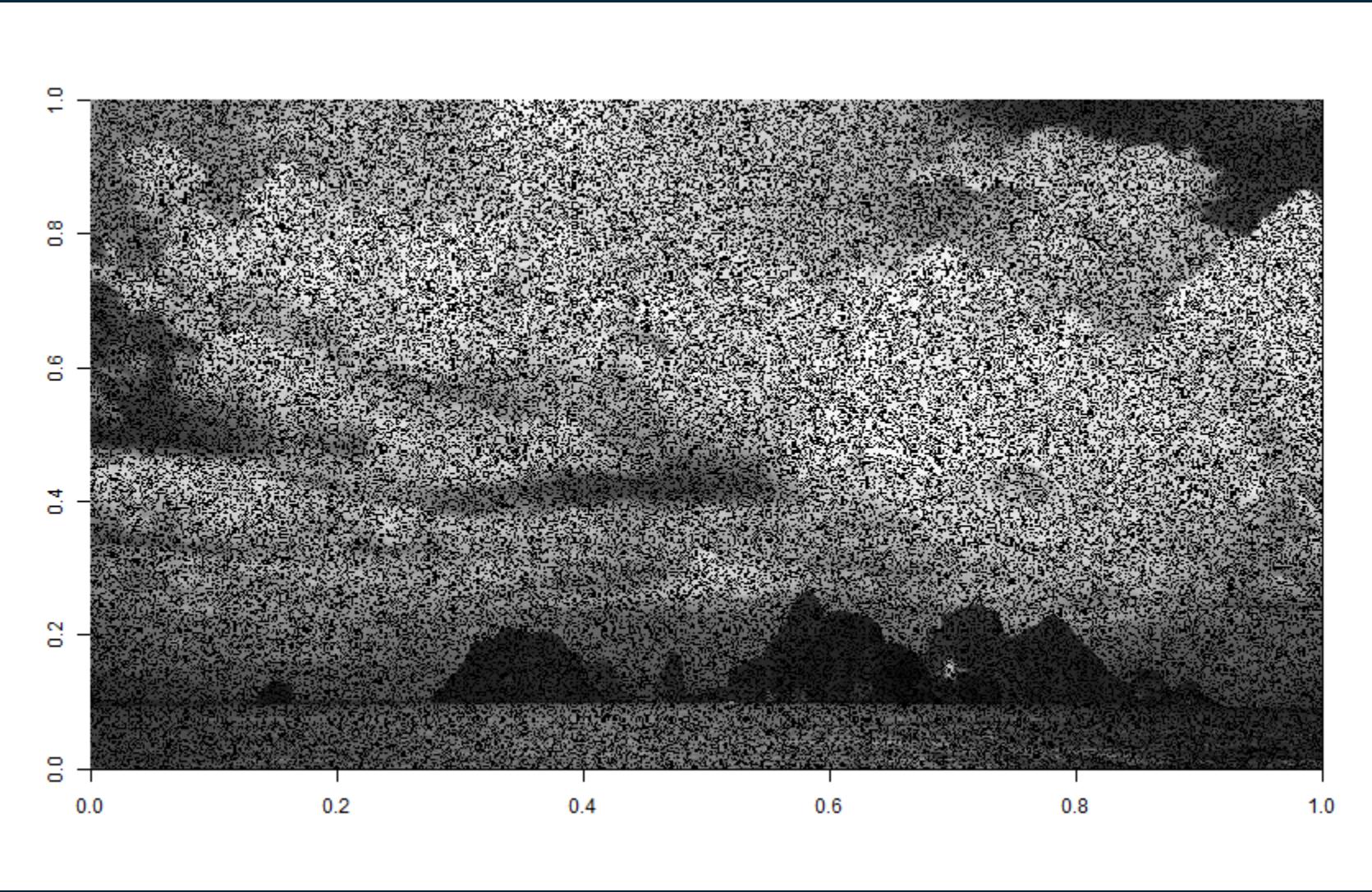
$$x_{ik} = x_{ik} - \alpha(-2(R_{ij} - x_i y_j)y_{kj})$$
$$y_{kj} = y_{kj} - \alpha(-2(R_{ij} - x_i y_j)x_{ik})$$

Gradient Descent in R

```
X[i,k] <- X[i,k] - alpha * (-2 * (eij) * Y[k,j])
Y[k,j] <- Y[k,j] - alpha * (-2 * (eij) * X[i,k])
```



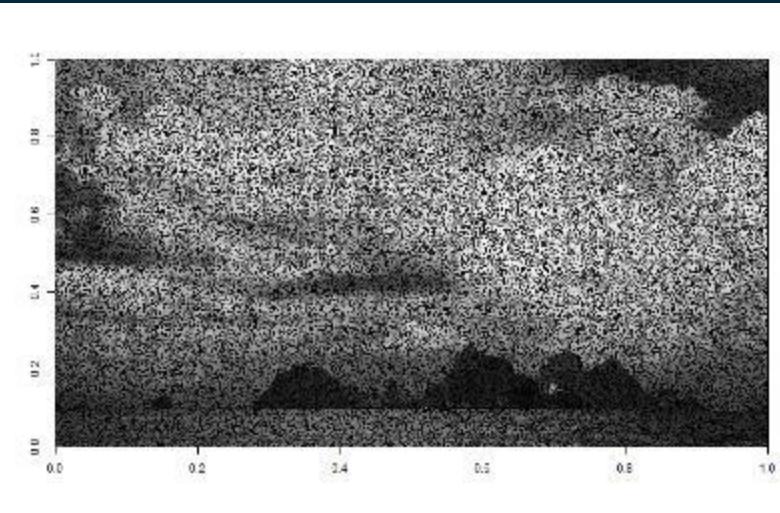
Pixel imputation : Sample 1 - corrupted



Pixel imputation : Sample 1 - generated



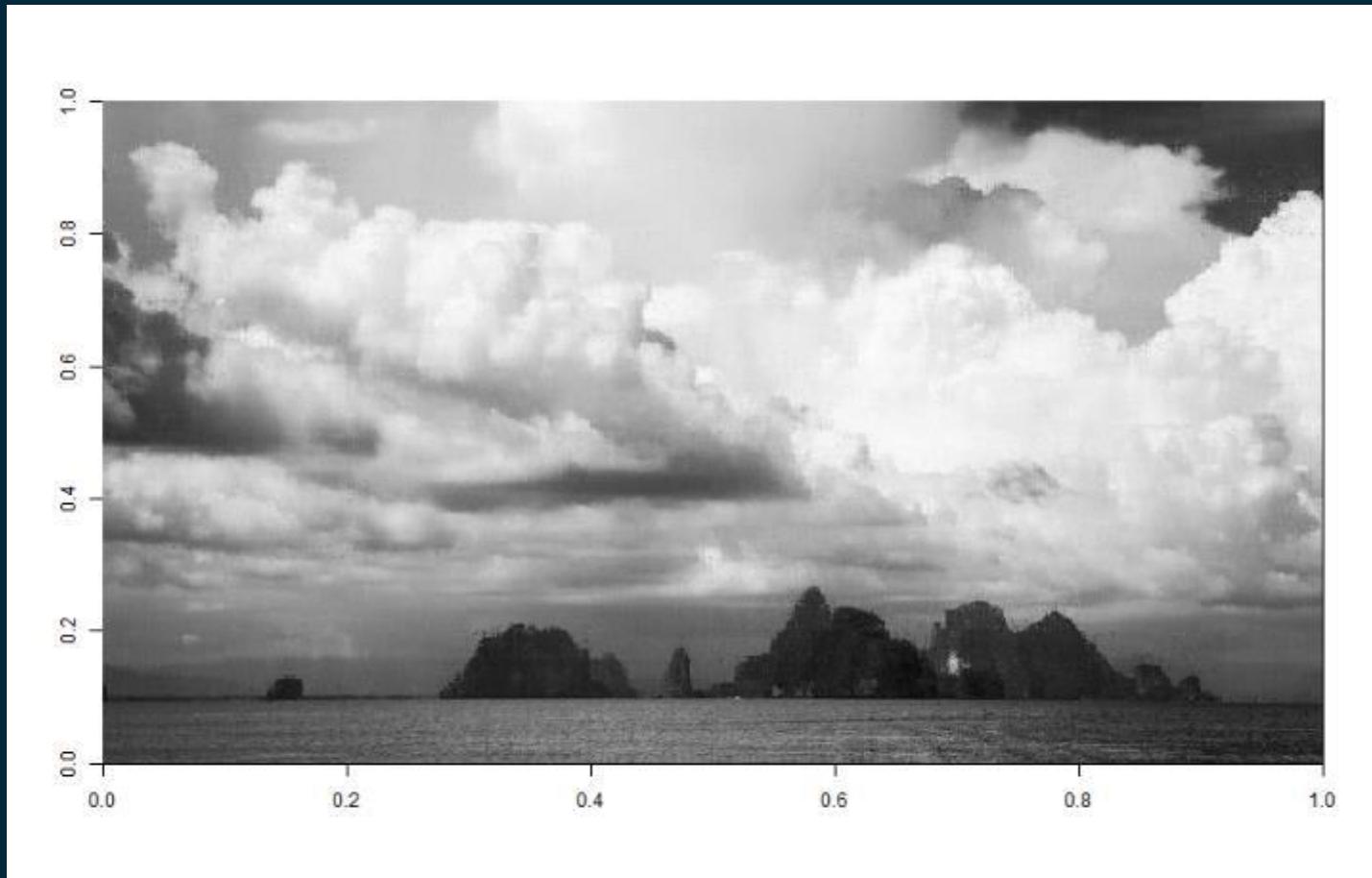
Pixel imputation : Sample 1 - corrected



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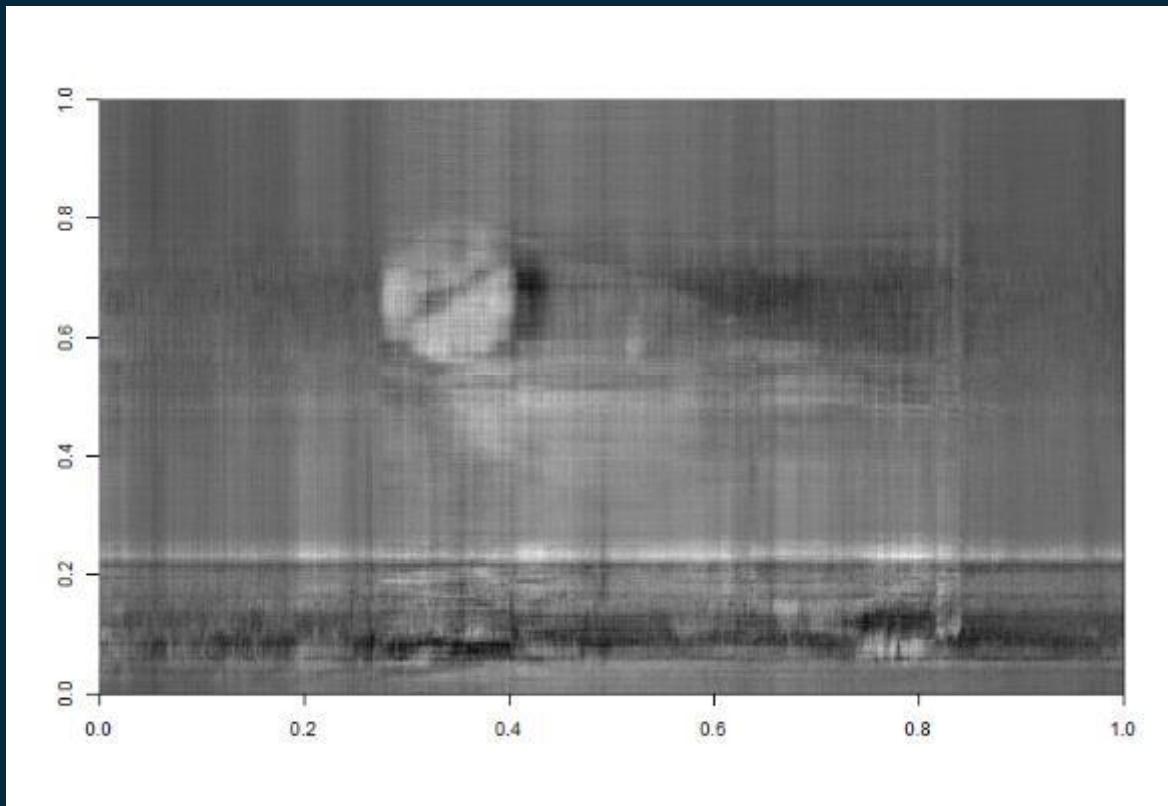
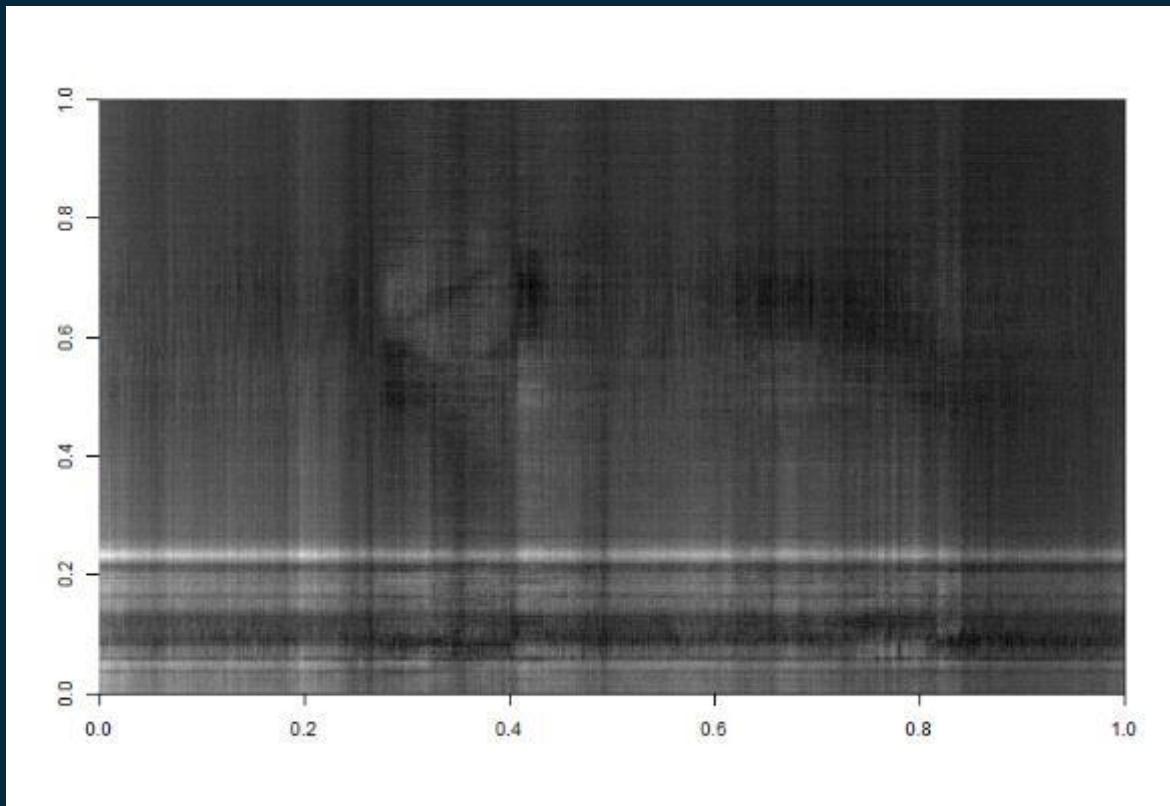
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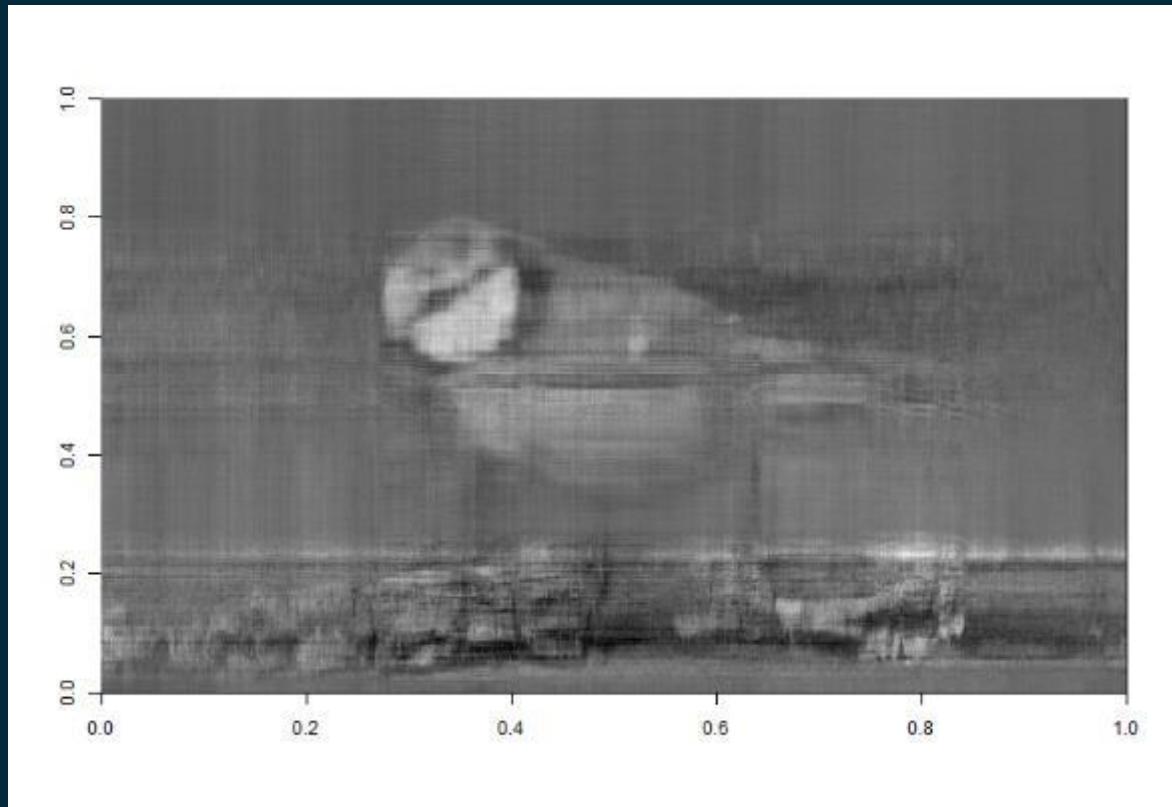
Visual of incremental progression



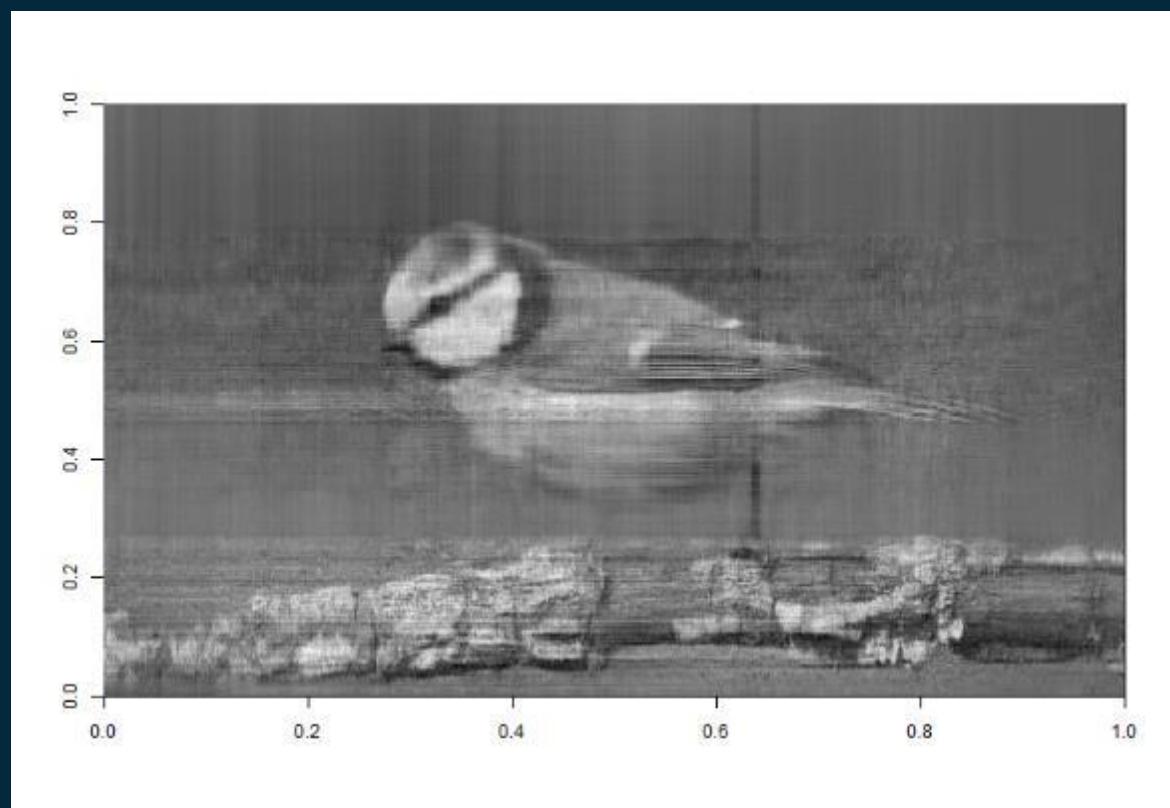
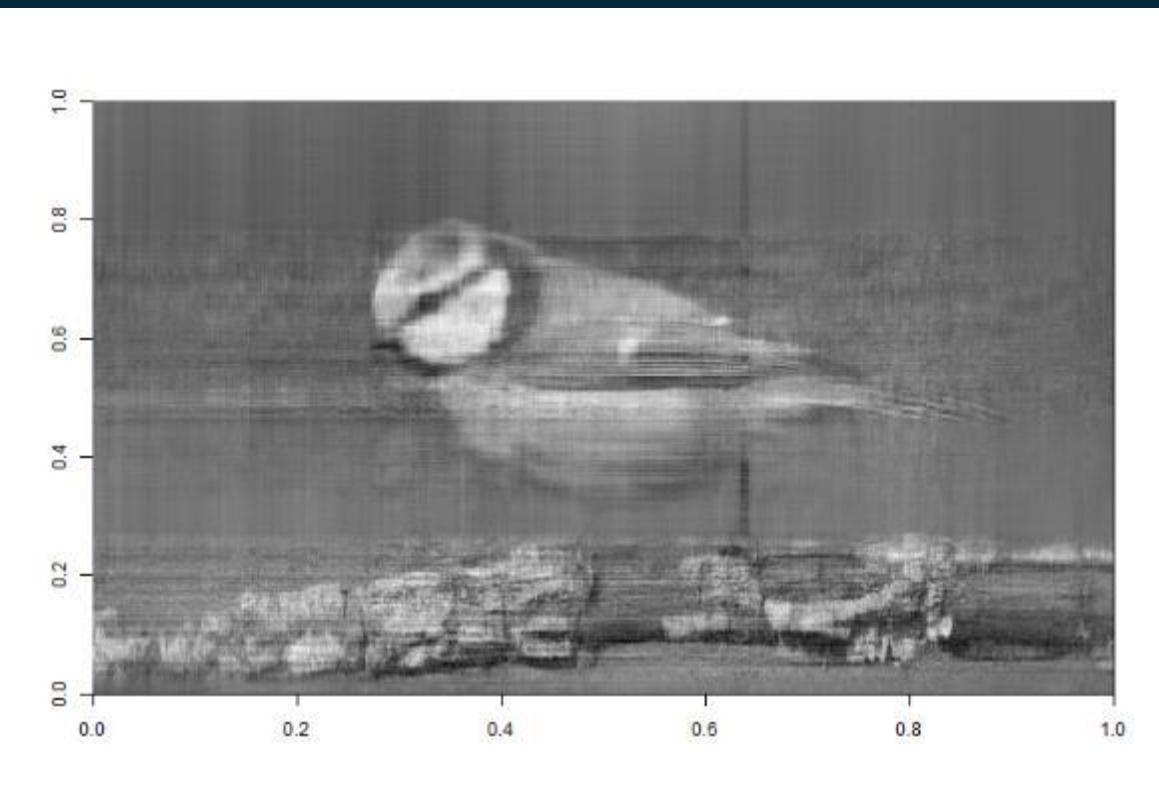
Incremental progression



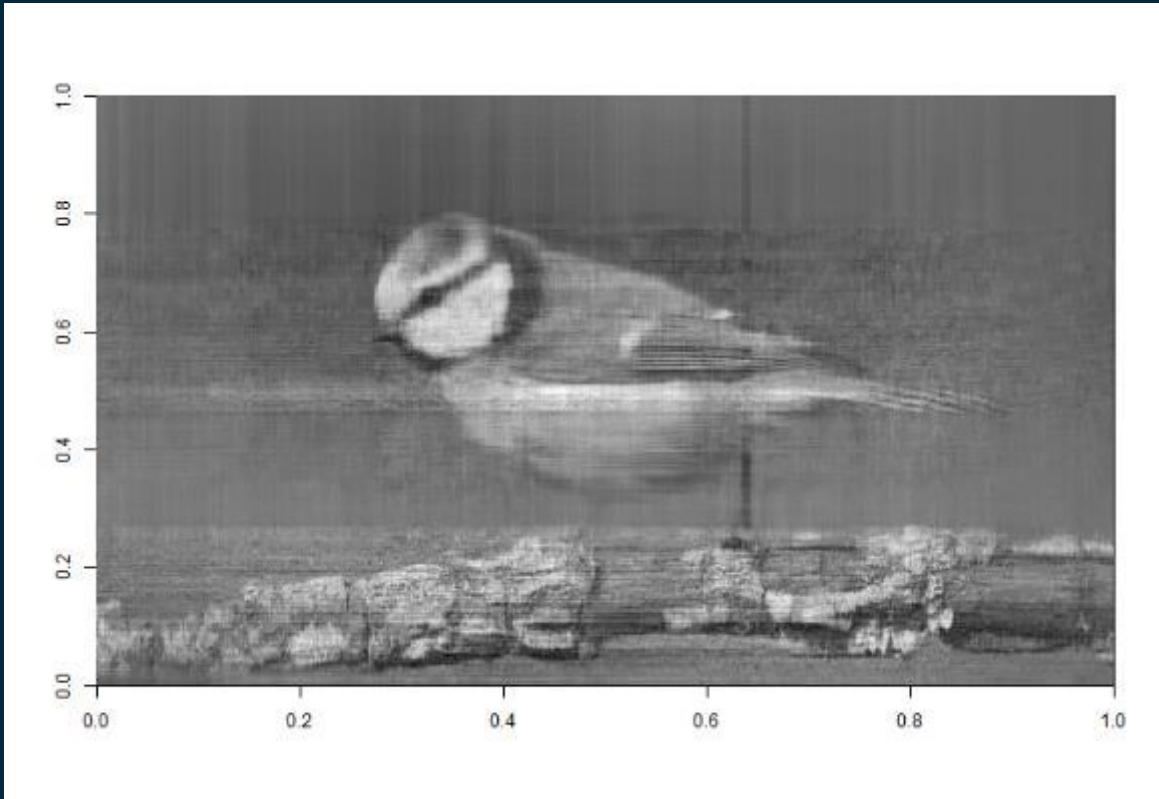
Incremental progression



Incremental progression



Incremental progression



Kudos to Albert Au Yeung

- Albert Au Yeung
Machine Learning Engineer, Hong Kong
- Python Funk MF tutorial code
- Extended for images and parallelism



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