

Estimate Null Correlation in MASH (OLD)

Yuxin Zou

November 30, 2018

1 Background

The MASH model is

$$\hat{\mathbf{b}}_j | \mathbf{b}_j, \hat{\mathbf{S}}_j \sim N_R(\mathbf{b}_j, \hat{\mathbf{S}}_j \mathbf{V} \hat{\mathbf{S}}_j) \quad (1.1)$$

$$\mathbf{b}_j | \boldsymbol{\pi} \sim \sum_{k=1}^K \sum_{l=1}^L \pi_{kl} N_R(\mathbf{0}, \omega_l \mathbf{U}_k) \quad (1.2)$$

Let $P = KL$, $\Sigma_p = \omega_l \mathbf{U}_k$. We can re-write 1.2 as

$$\mathbf{b}_j | \boldsymbol{\pi} \sim \sum_{p=1}^P \pi_p N_R(\mathbf{0}, \Sigma_p) \quad (1.3)$$

We want to estimate \mathbf{V} and $\boldsymbol{\pi}$ by maximum likelihood.

$$p(\hat{\mathbf{B}}) = \prod_{j=1}^J p(\hat{\mathbf{b}}_j) = \prod_{j=1}^J \sum_{p=1}^P \pi_p N_R(\hat{\mathbf{b}}_j; \mathbf{0}, \hat{\mathbf{S}}_j \mathbf{V} \hat{\mathbf{S}}_j + \Sigma_p) \quad (1.4)$$

Specifically, we estimate them by coordinate ascend. Given \mathbf{V} , we estimate $\boldsymbol{\pi}$ by solving a convex problem. Given $\boldsymbol{\pi}$, we want to estimate \mathbf{V} by maximum likelihood.

2 Method

It is hard to estimate \mathbf{V} by maximizing log of (1.4), so we use EM algorithm. We augment each $\hat{\mathbf{b}}_j$ with corresponding \mathbf{b}_j . The complete likelihood is

$$p(\hat{\mathbf{B}}, \mathbf{B}) = \prod_{j=1}^J N_R(\hat{\mathbf{b}}_j; \mathbf{b}_j, \hat{\mathbf{S}}_j \mathbf{V} \hat{\mathbf{S}}_j) \sum_{p=1}^P [\pi_p N_R(\mathbf{b}_j; \mathbf{0}, \Sigma_p)] \quad (2.1)$$

2.1 E step

Taking expectations of log (2.1), we have

$$\mathbb{E}_{\mathbf{B}|\hat{\mathbf{B}}} \log p(\hat{\mathbf{B}}, \mathbf{B}) \quad (2.2)$$

$$= \mathbb{E}_{\mathbf{B}|\hat{\mathbf{B}}} \left[\sum_{j=1}^J \log N_R(\hat{\mathbf{b}}_j; \mathbf{b}_j, \hat{\mathbf{S}}_j \mathbf{V} \hat{\mathbf{S}}_j) + \log \sum_{p=1}^P [\pi_p N_R(\mathbf{b}_j; \mathbf{0}, \Sigma_p)] \right] \quad (2.3)$$

$$= \sum_{j=1}^J -\frac{1}{2} \log |\mathbf{V}| - \log |\hat{\mathbf{S}}_j| - \frac{1}{2} \mathbb{E}_{\mathbf{b}_j|\hat{\mathbf{b}}_j} \left[(\hat{\mathbf{b}}_j - \mathbf{b}_j)^T \hat{\mathbf{S}}_j^{-1} \mathbf{V}^{-1} \hat{\mathbf{S}}_j^{-1} (\hat{\mathbf{b}}_j - \mathbf{b}_j) \right] + C \quad (2.4)$$

where C is a constant that does not depend on \mathbf{V} .

2.2 M step

We maximize (2.2) over \mathbf{V} . There is a constraint on \mathbf{V} , the diagonal of \mathbf{V} must be 1. Let $\mathbf{V} = \mathbf{D}\mathbf{C}\mathbf{D}$, \mathbf{C} is the covariance matrix, $\mathbf{D} = \text{diag}(1/\sqrt{\mathbf{C}_{jj}})$.

$$f(\mathbf{C}) = \sum_{j=1}^J -\frac{1}{2} \log |\mathbf{V}| - \frac{1}{2} \mathbb{E}_{\mathbf{b}_j|\hat{\mathbf{b}}_j} \left[(\hat{\mathbf{b}}_j - \mathbf{b}_j)^T \hat{\mathbf{S}}_j^{-1} \mathbf{V}^{-1} \hat{\mathbf{S}}_j^{-1} (\hat{\mathbf{b}}_j - \mathbf{b}_j) \right] \quad (2.5)$$

$$= \sum_{j=1}^J -\frac{1}{2} \log |\mathbf{D}\mathbf{C}\mathbf{D}| - \frac{1}{2} \mathbb{E}_{\mathbf{b}_j|\hat{\mathbf{b}}_j} \left[(\hat{\mathbf{b}}_j - \mathbf{b}_j)^T \hat{\mathbf{S}}_j^{-1} \mathbf{D}^{-1} \mathbf{C}^{-1} \mathbf{D}^{-1} \hat{\mathbf{S}}_j^{-1} (\hat{\mathbf{b}}_j - \mathbf{b}_j) \right] \quad (2.6)$$

$$f(\mathbf{C})' = \sum_{j=1}^J -\frac{1}{2} \mathbf{C}^{-1} + \frac{1}{2} \mathbf{C}^{-1} \mathbf{D}^{-1} \hat{\mathbf{S}}_j^{-1} \mathbb{E} \left((\hat{\mathbf{b}}_j - \mathbf{b}_j)(\hat{\mathbf{b}}_j - \mathbf{b}_j)^T | \hat{\mathbf{b}}_j \right) \hat{\mathbf{S}}_j^{-1} \mathbf{D}^{-1} \mathbf{C}^{-1} = 0 \quad (2.7)$$

$$\mathbf{C} = \frac{1}{J} \mathbf{D}^{-1} \left[\sum_{j=1}^J \hat{\mathbf{S}}_j^{-1} \mathbb{E} \left((\hat{\mathbf{b}}_j - \mathbf{b}_j)(\hat{\mathbf{b}}_j - \mathbf{b}_j)^T | \hat{\mathbf{b}}_j \right) \hat{\mathbf{S}}_j^{-1} \right] \mathbf{D}^{-1} \quad (2.8)$$

We can update \mathbf{C} and \mathbf{V} as

$$\hat{\mathbf{C}}_{(t+1)} = \hat{\mathbf{D}}_{(t)}^{-1} \frac{1}{J} \left[\sum_{j=1}^J \hat{\mathbf{S}}_j^{-1} \mathbb{E} \left[(\hat{\mathbf{b}}_j - \mathbf{b}_j)(\hat{\mathbf{b}}_j - \mathbf{b}_j)^T | \hat{\mathbf{b}}_j \right] \hat{\mathbf{S}}_j^{-1} \right] \hat{\mathbf{D}}_{(t)}^{-1} \quad (2.9)$$

$$\hat{\mathbf{D}}_{(t+1)} = \text{diag}(1/\sqrt{\hat{\mathbf{C}}_{(t+1)jj}}) \quad (2.10)$$

$$\hat{\mathbf{V}}_{(t+1)} = \hat{\mathbf{D}}_{(t+1)} \hat{\mathbf{C}}_{(t+1)} \hat{\mathbf{D}}_{(t+1)} \quad (2.11)$$

The resulting $\hat{\mathbf{V}}_{(t+1)}$ is equivalent as

$$\hat{\mathbf{C}}_{(t+1)} = \frac{1}{J} \left[\sum_{j=1}^J \hat{\mathbf{S}}_j^{-1} \mathbb{E} \left[(\hat{\mathbf{b}}_j - \mathbf{b}_j)(\hat{\mathbf{b}}_j - \mathbf{b}_j)^T | \hat{\mathbf{b}}_j \right] \hat{\mathbf{S}}_j^{-1} \right] \quad (2.12)$$

$$\hat{\mathbf{D}}_{(t+1)} = \text{diag}(1/\sqrt{\hat{\mathbf{C}}_{(t+1)jj}}) \quad (2.13)$$

$$\hat{\mathbf{V}}_{(t+1)} = \hat{\mathbf{D}}_{(t+1)} \hat{\mathbf{C}}_{(t+1)} \hat{\mathbf{D}}_{(t+1)} \quad (2.14)$$

We notice that updating $\hat{\mathbf{V}}$ requires the posterior of \mathbf{b}_j , which is obtained by mash model.

The algorithm is

Algorithm 1 Estimate Null Correlation

Require: mash data, covariance matrices \mathbf{U}_S , $\boldsymbol{\pi}$, initial value of \mathbf{V}

- 1: **repeat**
 - 2: E step: compute the posterior distribution of \mathbf{b}
 - 3: Update $\mathbf{C} \leftarrow$ 2.12
 - 4: Convert \mathbf{C} to $\mathbf{V} \leftarrow$ 2.14
 - 5: Compute loglikelihood
 - 6: **until** loglikelihood does not change
 - 7: **return** \mathbf{V}
-